

OSCILLATIONS OF n -th ORDER FUNCTIONAL DIFFERENTIAL EQUATIONS WITH PERTURBATIONS (*)

by LU-SAN CHEN and CHEH-CHIH YEH (in Taiwan) (**)

SOMMARIO. - Di recente, si è riscontrato un crescente interesse per lo studio di equazioni differenziali di ordine n in cui figura l'operatore differenziale di ordine n

$$L_0 x(t) = x(t), \quad L_i x(t) = \frac{1}{r_i(t)} \frac{d}{dt} L_{i-1} x(t), \quad 1 \leq i \leq n,$$

$$r_n(t) = 1,$$

che da luogo a termini smorzati.

In questo lavoro, vengono studiati criteri oscillatori per le soluzioni limitate di equazioni funzionali di ordine n , con argomenti devianti di tipo generale, aventi la forma

$$(E) \quad L_n x(t) + H(t, x[g_1(t)]) = Q(t, x[g_2(t)]), \quad n \text{ even}$$

e vengono date condizioni sufficienti per H e Q , tali da assicurare che tutte le soluzioni limitate di (E) siano oscillatorie.

SUMMARY. - Recently, there is an increasing interest in studying the n -th order differential equations involving the so called n -th order r -derivative of x

$$L_0 x(t) = x(t), \quad L_i x(t) = \frac{1}{r_i(t)} \frac{d}{dt} L_{i-1} x(t), \quad 1 \leq i \leq n,$$

$$r_n(t) = 1,$$

which causes damped terms.

Here, are studied the oscillatory criteria of bounded solutions of n -th

(*) Pervenuto in Redazione il 7 giugno 1978.

This research was supported by the National Science Council.

(**) Indirizzo degli Autori: Department of Mathematics - National Central University - Chung-Li - Taiwan 320 (Republic of China).

order functional differential equations with general deviating arguments of the form

$$(E) \quad L_n x(t) + H(t, x[g_1(t)]) = Q(t, x[g_2(t)]), \quad n \text{ even}$$

and are given the sufficient conditions on H and Q , which guarantee that all bounded solutions of (E) are oscillatory.

1. Introduction.

In this paper we consider the n -th order functional differential equations with general deviating arguments of the form

$$(E) \quad L_n x(t) + H(t, x[g_1(t)]) = Q(t, x[g_2(t)]), \quad n \text{ even},$$

where the differential operator L_n is recursively defined by

$$L_0 x(t) = x(t), \quad L_i x(t) = \frac{1}{r_i(t)} \frac{d}{dt} L_{i-1} x(t), \quad 1 \leq i \leq n,$$

$$r_n(t) = 1.$$

We note that $g(t)$ is a general deviating argument, that is, it is allowed to be advanced ($g(t) \geq t$), or retarded ($g(t) \leq t$) or otherwise. A solution $x(t)$ of (E) is said to be continuable if it exists on some ray $[a, \infty)$, $a > 0$. A nontrivial solution of (E) is *oscillatory* if it is continuable and has arbitrary large zeros. By a nonoscillatory solution we mean a continuable solution which is not oscillatory. The term « solution » for the remainder of this work will mean a nontrivial continuable solution.

The motivation for this study comes from a recent article by Kartsatos [4]. In [4], Kartsatos considers a special class of n -th order functional differential equation of the form

$$x^{(n)}(t) + H(t, x[g_1(t)]) = Q(t, x[g_2(t)]), \quad n \text{ even},$$

and derives some oscillation criteria. We also refer to the works of Chen-Yeh [1] - [2], Kartsatos [3] and Lovelady [5].

The following assumptions are made without further mention:

$$(a) \quad r_i \in C(R_+ \equiv [0, \infty), R_+ \setminus \{0\}),$$

and

$$\int_0^{\infty} r_i(t) dt = \infty, \quad 1 \leq i \leq n-1;$$

$$(b) \quad g_i \in C(R_+, R = (-\infty, \infty))$$

and

$$\lim_{t \rightarrow \infty} g_j(t) = \infty \quad \text{for } j=1, 2;$$

(c) $H, Q \in C(R_+ \times R, R)$, $H(t, u)$ is increasing in u and $uH(t, u) \geq 0$ for $u \neq 0$.

Our purpose here is to give the sufficient conditions on H and Q under which all bounded solutions of (E) are oscillatory.

2. Main results.

THEOREM 1. Let

(i) for each $\alpha > 0$ there exists a function $Q_\alpha \in C(R_+, R_+)$ such that

$$|Q(t, u)| \leq Q_\alpha(t)$$

for each $u \in R$ with $|u| \leq \alpha$;

(ii) for each $c > 0$, $\alpha > 0$

$$\int_0^{\infty} \omega_{n-1}(t) \{H(t, \pm c) \mp Q_\alpha(t)\} dt = \pm \infty,$$

where $\omega_{n-1}(t)$ is defined by

$$\omega_1(t) = \int_0^t r_1(s) ds, \quad \omega_x(t) = \int_0^t r_x(s) \omega_{x-1}(s) ds,$$

$$x=2, 3, \dots, n-1.$$

Then if $x(t)$ is a bounded eventually positive (negative) nonoscillatory solution of (E), there exists a sequence $\{\bar{t}_n\}$, $n=1, 2, \dots$ such that

$\lim_{n \rightarrow \infty} \bar{t}_n = \infty$, and $H(\bar{t}_n, x[g_1(\bar{t}_n)] \leq Q(\bar{t}_n, x[g_2(\bar{t}_n)]), (H(\bar{t}_n, x[g_1(\bar{t}_n)]) \geq Q(\bar{t}_n, x[g_2(\bar{t}_n)]))$. Now, in addition to the above assume that $g_1(t) \equiv g_2(t)$ and that the inequality

$$H(t_n, x_n) \leq Q(t_n, x_n) \quad (H(t_n, x_n) \geq Q(t_n, x_n))$$

for a sequence $\{t_n\}$ with $\lim_{n \rightarrow \infty} t_n = \infty$ and a sequence $\{x_n\}$ which is positive (negative) and bounded, is impossible; then every bounded solution of (E) is oscillatory.

PROOF. Let $x(t)$ be a bounded eventually positive nonoscillatory solution of (E). Then there exist $t_1 \geq 0$ and t_2 such that $x(t) > 0$ for $t \geq t_1$ and $g_j(t) \geq t_1$ for $t \geq t_2$ and $j=1, 2$. Thus $x[g_j(t)] > 0$ for $t \geq t_2$ and $j=1, 2$. Since $x(t)$ is bounded, there is a $\alpha > 0$ such that $|x(t)| < \alpha$ for each $t \geq t_1$. Thus, by (i),

$$(1) \quad |Q(t, x[g_2(t)])| \leq Q_\alpha(t)$$

for $t \geq t_2$. Assume that

$$H(t, x[g_1(t)]) - Q(t, x[g_2(t)]) > 0$$

for $t \geq T$, where $T \geq t_2$ is a fixed number. Then, by (E), $L_n x(t) < 0$ for $t \geq T$. It follows from Lemma of [1] (or, cf. [4]) that

$$(2) \quad (-1)^{x+1} L_x x(t) > 0, \quad x=1, 2, \dots, n-1$$

for $t \geq T$. If T is large enough, then, for $t \geq T$

$$(-1)^{x+1} L_x x[g_j(t)] > 0, \quad x=1, 2, \dots, n-1, \quad j=1, 2.$$

It follows from $x'[g_1(t)] > 0$ for $t \geq T$ that

$$x[g_1(t)] > x[g_1(T)] = c.$$

Thus

$$(3) \quad H(t, x[g_1(t)]) \geq H(t, c).$$

From (E), (1) and (3), we have

$$\int_T^t \omega_{n-1}(s) L_n x(s) ds + \\ + \int_T^t \omega_{n-1}(s) \{H(s, x[g_1(s)]) - Q(s, x[g_2(s)])\} ds = 0$$

i. e.

$$(4) \quad x(t) \geq x(T) + D(t) - D(T) + \int_T^t \omega_{n-1}(s) \{H(s, c) - Q_\alpha(s)\} ds$$

where $D(t) = \sum_{i=1}^{n-1} (-1)^{i+1} \omega_i(t) L_i x(t)$.

Hence, by (2), (4) and (ii),

$$x(t) > x(T) - D(T) + \int_T^t \omega_{n-1}(s) \{H(s, c) - Q_\alpha(s)\} ds \rightarrow \infty$$

as $t \rightarrow \infty$, a contradiction. Consequently, there exists at least $\bar{t}_1 \geq T$ such that

$$H(\bar{t}_1, x[g_1(\bar{t}_1)]) - Q(\bar{t}_1, x[g_2(\bar{t}_1)]) \leq 0.$$

Since T was arbitrary, it follows that there exists a sequence $\{\bar{t}_n\}$, $n=1, 2, \dots$, such that $\bar{t}_n \geq t_2$ and

$$(5) \quad H(\bar{t}_n, x[g_1(\bar{t}_n)]) - Q(\bar{t}_n, x[g_2(\bar{t}_n)]) \leq 0, \quad n=1, 2, \dots,$$

Similarly, we can prove the case for an eventually negative bounded nonoscillatory solution $x(t)$. As far as the second part is concerned, it is obvious from (5) with $g_1(t_n) = g_2(t_n)$ and the corresponding inequality for a negative solution $x(t)$. This completes our proof.

REMARK 1. Taking $r_i(t) = 1$ for $i=1, 2, \dots, n-1$, a result of Kartsatos (Theorem 1, [3]) is a special case of our theorem.

We now state an auxiliary lemma, which is due to Chen-Yeh [2].

LEMMA. Consider the equation

$$(6) \quad L_n x(t) + H(t, x(t)) = 0,$$

and the inequality

$$(7) \quad L_n x(t) + H(t, x(t)) \leq 0,$$

where $H \in C(R \times R, R)$ is increasing with respect to x .

If there exists a solution (bounded solution) $x(t)$ of (7) with $x(t_1) = u_1 > 0$ for some $t_1 > 0$ and $x'(t) \geq 0$, $t \in [t_1, \infty)$, then there is a solution (bounded solution) $y(t)$ of (6) with $y(t_2) = u_1$ and $y'(t) \geq 0$, $t \in [t_2, \infty)$ for some $t_2 \geq t_1$.

THEOREM 2. Let $H(t, u)$ be strictly increasing in u and such that for every $t \in R_+$, $\mu_1, \mu_2 \in R$ with $\mu_1 \mu_2 > 0$, $|\mu_1| < |\mu_2|$,

$$|H(t, \mu_1)| \leq k(\mu_1, \mu_2) |H(t, \mu_2)|,$$

where k is a constant depending on μ_1, μ_2 with $k(\mu_1, \mu_2) \in (0, 1)$.

Let every solution (bounded solution) of

$$(8) \quad L_n x(t) + \mu H(t, x(t)) = 0$$

be oscillatory for every $\mu > 0$. Let the inequality

$$(9)_1 \quad L_n x(t) + H(t, x(t)) \leq Q(t)$$

have an eventually positive solution $x_1(t)$, and the inequality

$$(9)_2 \quad L_n x(t) + H(t, x(t)) \geq Q(t)$$

have an eventually negative solution $x_2(t)$ such that

$$(10) \quad \lim_{t \rightarrow \infty} x_j(t) = 0, \quad j = 1, 2.$$

Then every solution (bounded solution) of

$$(11) \quad L_n x(t) + H(t, x(t)) = Q(t)$$

is oscillatory.

PROOF. Let $x_2(t) < 0$, $t \geq t_1 > 0$, satisfy $(9)_2$, and let every solution of (8) be oscillatory. If $x(t)$ is a positive solution of (11), then $u(t) \equiv$

$\equiv x(t) - x_2(t)$ is a solution of

$$(12) \quad L_n u(t) + H(t, u(t) + x_2(t)) - H(t, x_2(t)) \leq 0.$$

Assume that $u(t) > 0$ for $t \geq t_2 \geq t_1$. Then $L_n u(t) < 0$ for $t \geq t_2$. Since n is even, $u'(t) > 0$ for $t \geq t_2$, where t_2 is large enough. We choose $\varepsilon > 0$ so that $\varepsilon < \frac{1}{2} u(t_2)$ and, $|x_2(t)| < \varepsilon$ for every $t \geq t_3$, for some $t_3 \geq t_2$. It follows from (12) that

$$(13) \quad \begin{aligned} L_n u(t) + H(t, u(t) - \varepsilon) - H(t, \varepsilon) \leq \\ \leq L_n u(t) + H(t, u(t) + x_2(t)) - H(t, x_2(t)) \leq 0 \end{aligned}$$

for $t \geq t_3$. Since $u(t) - 2\varepsilon > u(t_2) - 2\varepsilon > 0$ for $t \geq t_3$,

$$(14) \quad H(t, u(t) - \varepsilon) - H(t, \varepsilon) > 0, \quad t \geq t_3.$$

Let $v(t) \equiv u(t) - \varepsilon$, then $v(t), t \geq t_3$ is a positive solution of

$$(15) \quad L_n v(t) + H(t, v(t)) - H(t, \varepsilon) \leq 0, \quad t \geq t_3,$$

and such that $v'(t) > 0$ and $v(t) > \varepsilon$ for $t \geq t_3$. It follows from Lemma that this is also true for the equation

$$(16) \quad L_n z(t) + H(t, z(t)) - H(t, \varepsilon) = 0.$$

Let $z(t)$ be such a solution of (16) with $z(t), z'(t) > 0$ for $t > t_3$ and $z(t_3) > \varepsilon$. Since $H(t, x)$ is strictly increasing in x ,

$$\begin{aligned} H(t, \varepsilon) &< k(\varepsilon, z(t_3)) H(t, z(t_3)) < \\ &< k(\varepsilon, z(t_3)) H(t, z(t)) \end{aligned}$$

for $t \geq t_3$. Letting $\mu = 1 - k(\varepsilon, z(t_3))$, we obtain that

$$(17) \quad L_n W(t) + \left\{ 1 - \frac{H(t, \varepsilon)}{H(t, z(t))} \right\} H(t, W(t)) = 0$$

have a positive solution $z(t), t \geq t_3$, with the coefficient of $H(t, W(t))$ bounded below by the constant μ . Since every solution of (8) is oscillatory for every $\mu \geq 0$, we obtained by Theorem of [2], that every solution of (17) must also be oscillatory, a contradiction. Hence there

exists a sequence $\{t_m\}$, $m=1, 2, \dots$, such that $\lim_{m \rightarrow \infty} t_m = \infty$ and $x(t_m) < x_2(t_m) < 0$, $m=1, 2, \dots$, which contradicts the positiveness of $x(t)$. Similarly, we can prove the case where $x_1(t)$ is a positive solution of (9)₁ and the case where every solution of (8) is bounded oscillatory.

REMARK 2. Taking $r_i(t)=1$ for $i=1, 2, \dots, n-1$, a result of Kartsatos (Theorem 2.1, [4]) is a special case of our theorem.

From the proof of Theorem 2, we can obtain the following two corollary.

COROLLARY 1. *Let the assumption on H , Q of Theorem 2 be satisfied. Let $x_1(t)$ is a solution of (9)₁ with $\lim_{t \rightarrow \infty} x_1(t)=0$. If every solution of (8) is oscillatory (bounded oscillatory) for every $\mu > 0$, then every eventually positive (negative) [bounded and positive (bounded and negative)] solution $x(t)$ of (11) satisfies $\liminf_{t \rightarrow \infty} x(t)=0$.*

COROLLARY 2. *Let the assumption on H , Q of Theorem 2 be satisfied. Let $x_1(t)$ is an eventually positive (negative) solution of (11) with $\lim_{t \rightarrow \infty} x_1(t)=0$. Assume that $x_2(t)$ is another solution of (11) with the same property. If every bounded solution of (8) is oscillatory for every $\mu > 0$, then $x_1(t) - x_2(t)$ is an oscillatory function.*

REFERENCES

- [1] LU-SAN CHEN and CHEH-CHIH YEH, A comparison theorem for general n -th order functional differential nonlinear equations with deviating arguments, Rend. Accad. Naz. Lincei, 62 (1977), 168-172.
- [2] LU-SAN CHEN and CHEH-CHIH YEH, A note on n -th order differential inequalities, Rend. Accad. Naz. Lincei, 61 (1976), 580-584.
- [3] A. G. KARTSATOS, Oscillation and nonoscillation for perturbed differential equations, Hiroshima Math. J., 8 (1978), 1-10.
- [4] A. G. KARTSATOS, Analysis of the effect of certain forcings on the nonoscillatory solutions of even order equations, J. Austral. Math. Soc., 24 (1977), 234-244.
- [5] D. L. LOVELADY, On the oscillatory behavior of bounded solutions of higher order differential equations, J. Differential Equations, 19 (1975), 167-175.